

DISCOVERING TECHNOLOGICAL OPPORTUNITIES IN EXPLORING THE DEEP-SEA, EARTH, AND OUTER SPACE

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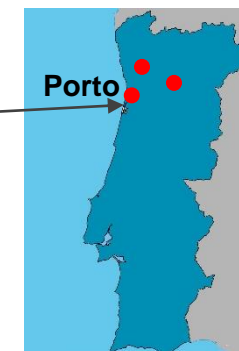


Research centers

- R&D non-profit research center and technology interface institution
- Researchers from multiple universities in northern Portugal
 - University of Porto
 - **Porto Polytechnic Institute - ISEP**
 - Univ. Minho
 - UTAD
- 725 researchers (350 PhDs) dedicated to R&D and advanced consulting



isep Instituto Superior de Engenharia do Porto



CRAS
Robotics and
Autonomous
Systems

CRIS
Robotics in
Industry and
Intelligent Systems

CITE
Innovation,
Technology and
Entrepreneurship

CESE
Enterprise
Systems
Engineering

CEGI
Industrial
Engineering and
Management

CAP
Applied
Photonics

CTM
Telecom.
and
Multimedia

C-BER
Biomedical
Engineering

CPES
Power
and Energy
Systems

CSIG
Information
Systems
and Computer
Graphics

LIAAD
Artificial
Intelligence
and Decision
Support

CRACS
Advanced
Computing
Systems

HASLab
High-
Assurance
Software



Center for Robotics and Autonomous Systems

Make robotic and other autonomous systems able to operate in **complex, unstructured** and **dynamic environments** with increasing levels of autonomy, by enhancing their perception, understanding, reasoning, decision, and interaction capabilities.

Motivation & Drivers

The Extension of the **Portuguese Continental Shelf**, and the **national Plan for Recovery and Resilience**.

Horizon Europe Missions

- Adaptation to Climate Change
- Restore our Ocean and Waters
- Climate-Neutral and Smart Cities

UN Sustainable Development Goals

- Clean Water and Sanitation
- Climate Action
- Life Below Water

RL1 – Navigation & Control

RL2 – Interaction with Environment

RL3 – Mapping & Real Time Perception

RL4 – Platforms & Operations

RLNew – Space Geo-Robotics and Geo-Technologies

INOV1 – Robotics systems prototyping and upscaling

INOV2 – Navigation and mapping

INOV3 – Component development for robotics systems

INOV4 – Underwater acoustics for positioning, navigation and communications

Robotics & Autonomous Systems Laboratory

- More than 1000m² of lab space
 - Large indoor space robot testing
- Two test tanks
 - 10 x 6 x 5 m
 - Underwater vision-based ground-truth system
- Hyperbaric chamber
 - 750 bar (7500m)
 - 400 bar (4000m)
- Production facilities
 - CNC, 3D printing etc.



Research Vessel - *Mar Profundo* -

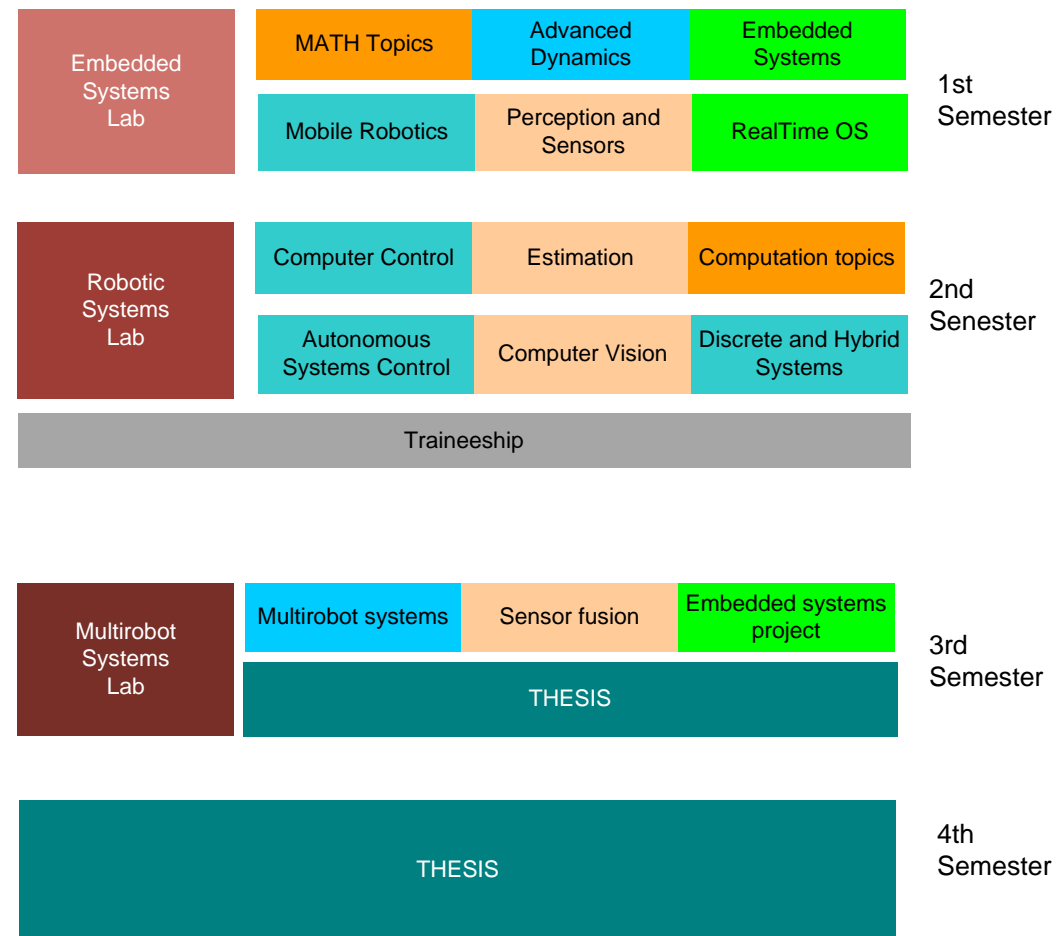
- Coastal research and technology development vessel
- Catamaran, 19m length
- A-frame 1.5 ton and 700 kg crane
- On board lab
- Capacity for 9 researchers
- Ocean operations, tailored for missions up to 60 nautical miles





Research support MSc. EEC - Autonomous systems

- **MSc. Electrical and Computer Engineering – Autonomous Systems**
- Trimester curricular units + semester laboratory
- Continuous work oriented and integrated with laboratory research work.
- **High degree of student participation in lab research activities**
- International networking
- Robotics competitions

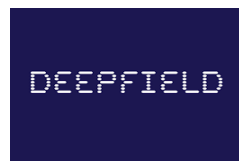


Scientific capability building & Research infrastructures

Scientific capacity building (H2020 CSA/Twinnings)



Strengthening Maritime Technology Research Center (finished)



Deep learning in field robotics: from conceptualization towards implementation (on going)

- Scientific training
- Joint research activities
- Summer/winter schools
- Research of excellence on the areas of marine technology and robotics and deep learning in field robotics



INESCTEC
ASSOCIATE LABORATORY
PORTUGAL



EDINBURGH CENTRE FOR
ROBOTICS



Universitat
de Girona



ViCOROB
COMPUTER VISION AND ROBOTICS



GIRONIA UNDERWATER
VISION AND ROBOTICS



UNIVERSITY
OF ABERDEEN



POLITECNICO
DI MILANO



MAX-PLANCK-GESELLSCHAFT



Universitat
de Girona



ViCOROB
COMPUTER VISION AND ROBOTICS

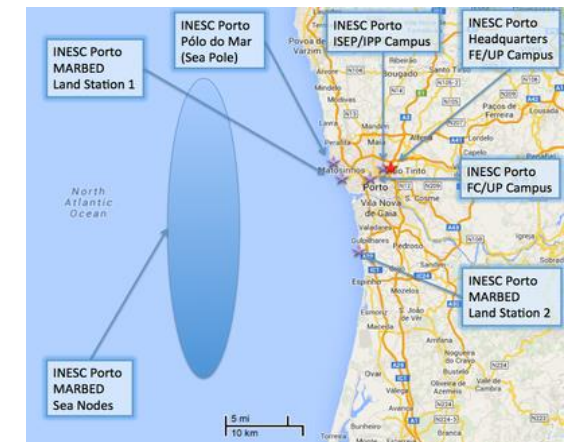
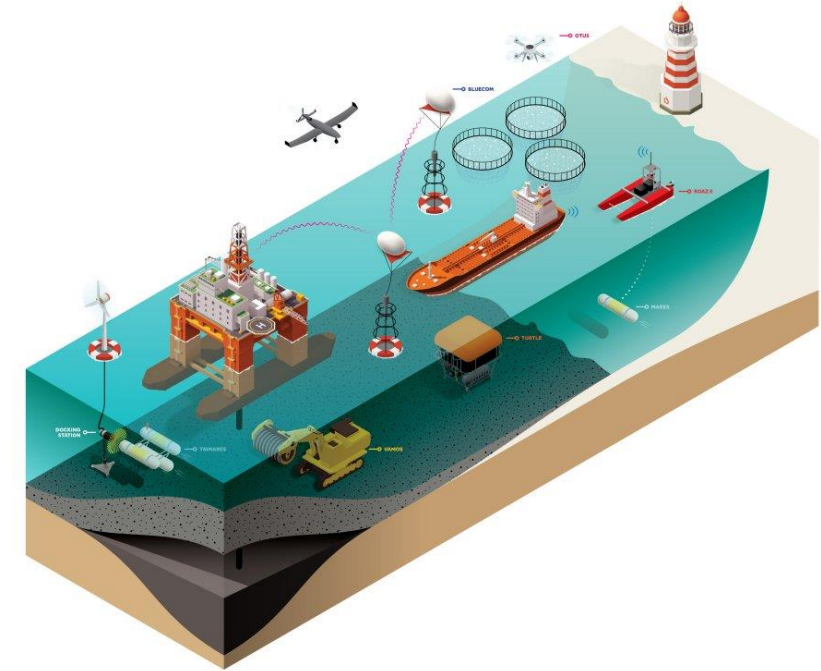


GIRONIA UNDERWATER
VISION AND ROBOTICS

TEC4Sea National research Infrastructure

- National Research Infrastructure for development of technology for the sea
- Integrated in national research infrastructure strategic plan (5.3 M€)
- Instrumented open sea area on the north Portuguese coast
- 20m long sea operations research and support ship
- Mobile laboratories and operations support
- Specialized sea technology labs and equipment

Support research, development, and test of marine robotics, telecommunications, and sensing technologies for monitoring and operating in the ocean





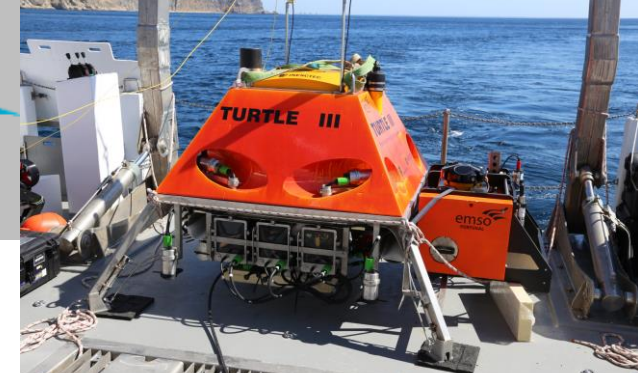
EMSO-PT



european
multidisciplinary
seafloor & water column
observatory



- Integrated in national research infrastructure strategic plan
- Part of European Multidisciplinary Seafloor Observatory (EMSO) - *Real time monitoring for long time periods environmental processes related with interaction between geospatial/biosphere/ hydrosphere*



Atlantis



The Atlantic
Testing Platform for
Maritime Robotics



- Establish a pioneer pilot infrastructure in the Atlantic Ocean
- Demonstrate key enabling robotic technologies for inspection and maintenance of offshore wind farms

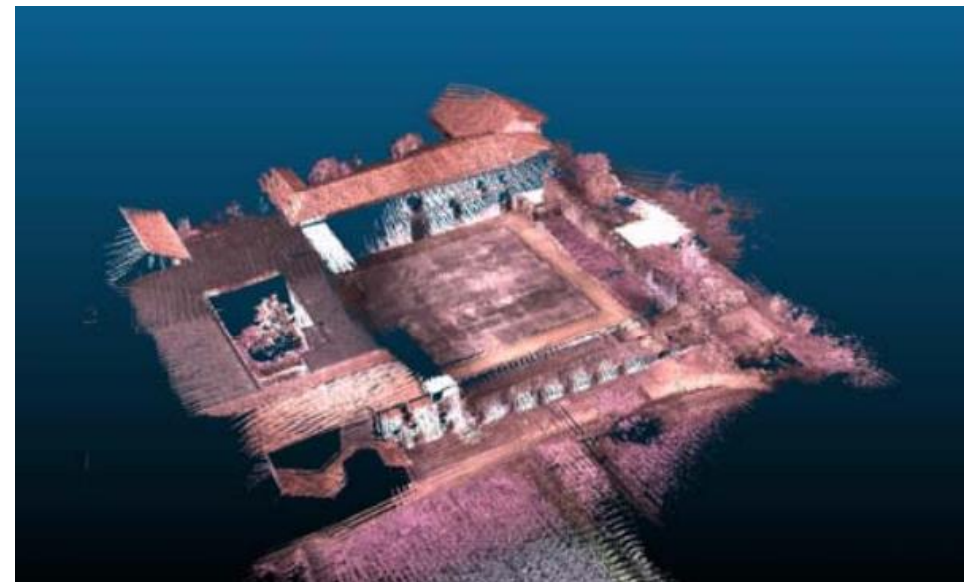
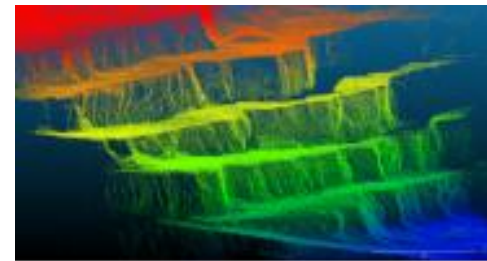
Aerial robotics

*Underground 3D
mapping and
reconstruction*

Aerial robotics

- Research
 - Perception and navigation
 - Hyperspectral imaging
 - 3D modeling
 - Semantic perception

- Applications
 - Security
 - Search and rescue
 - Disaster management
 - Mapping
 - Infrastructure inspection





MineHeritage

Historical Mining – tracing and learning from ancient materials and mining technology

Wider Society Learning project that intends to use Cultural Heritage, Mining and Raw Materials to create popular educational tools for the dissemination of the importance of Raw Materials to society through historic periods

ROBOTICS

INESC TEC
LABORATÓRIO ASSOCIADO
POLO DO ISEP



GeoTEC SYSTEM
STORK I | UAV

Made in INESC TEC, Portugal



Field Campaigns

FINAL OUTPUTS

GeoTec system | 3D mapping and imaging – Main Tunnel



Marine and Underwater robotics



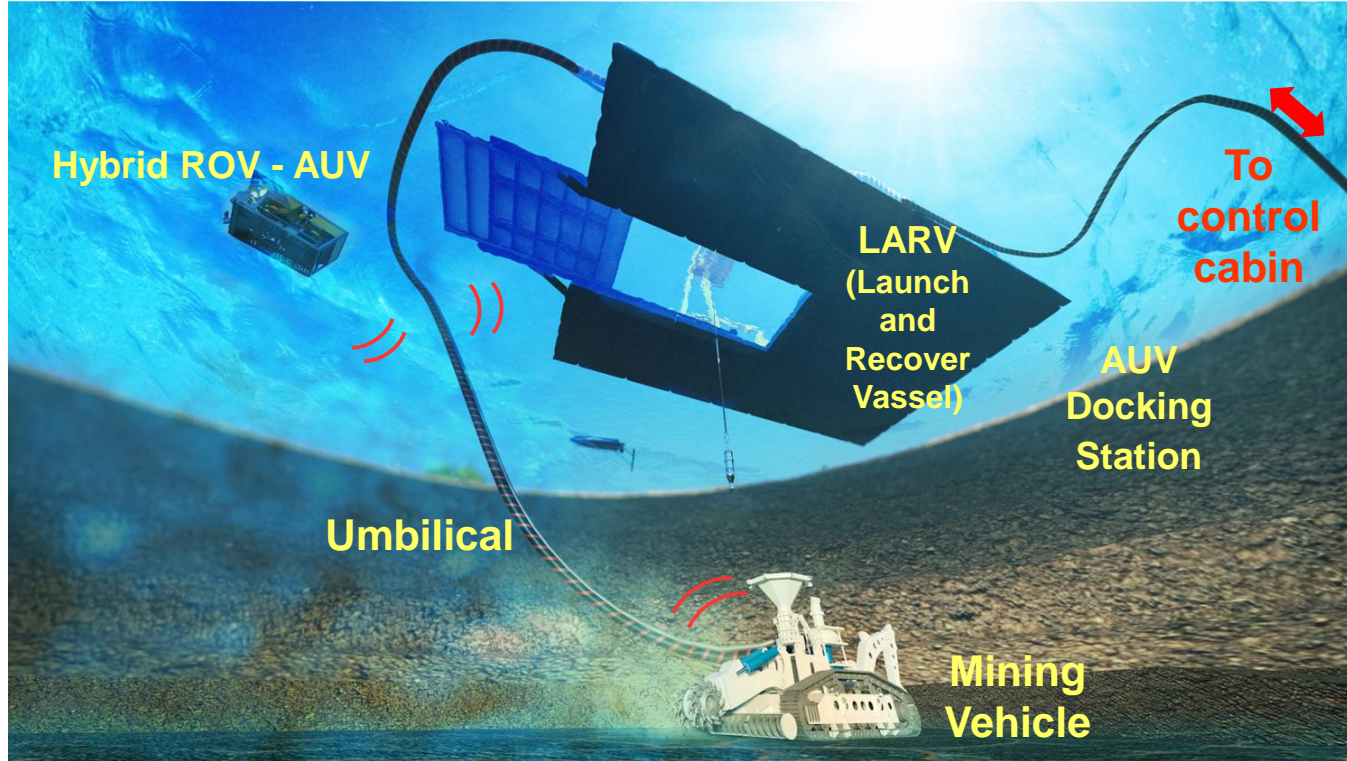
VAMOS – Viable Alternative Operating System



- EU H2020 Raw Materials project
- **New underwater, commercially viable robotic mining technology**
- 12.9 M€, 2015-2019, 17 partners, 9 countries
- Partners: BMT, SMD (UK), INESC TEC, Damen Dredging (NED), Trelleborg (NED), Sandvik (AU)...
- INESC TEC: Positioning, navigation and awareness system



VAMOS System Overview



Command and Control
VR based interface



Hybrid ROV / AUV



Remoted operated Mining Machine



Support Vessel

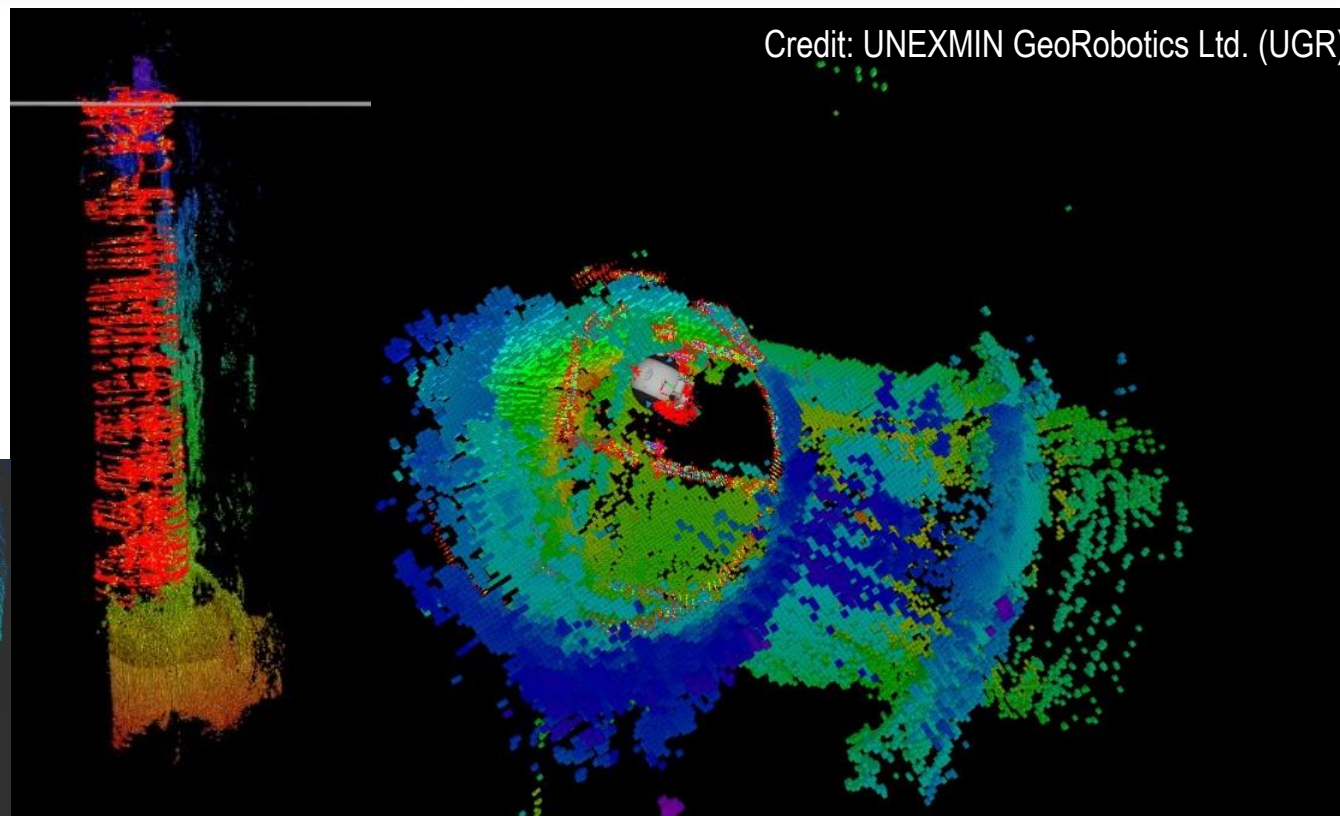
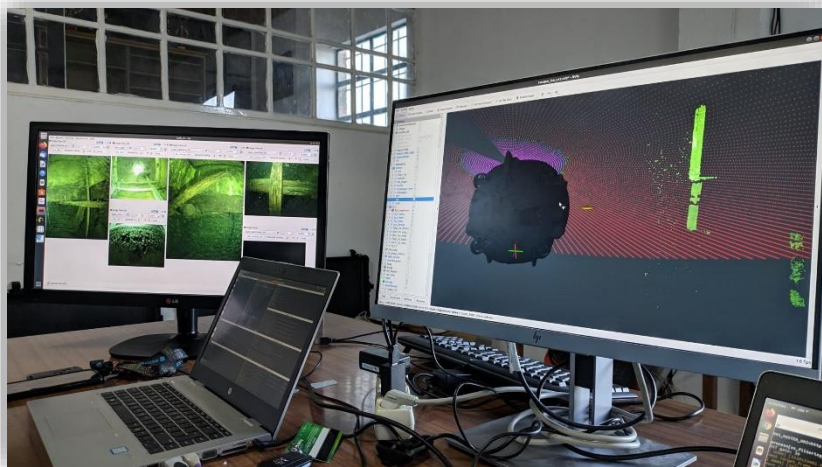


UNEXMIN Project

European Union's Horizon
H2020 research and innovation program
+ info: www.unexmin.eu

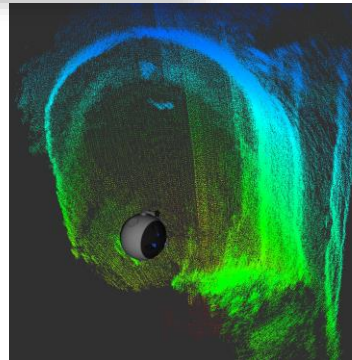
UNEXUP

Upscaling Project funded by EIT Raw Materials
+ info: www.unexup.eu



Credit: UNEXMIN GeoRobotics Ltd. (UGR)

- Challenging scenarios
- Mapping
- Perception
- Navigation and Localization



Future Perspectives & Future Geotechnologies

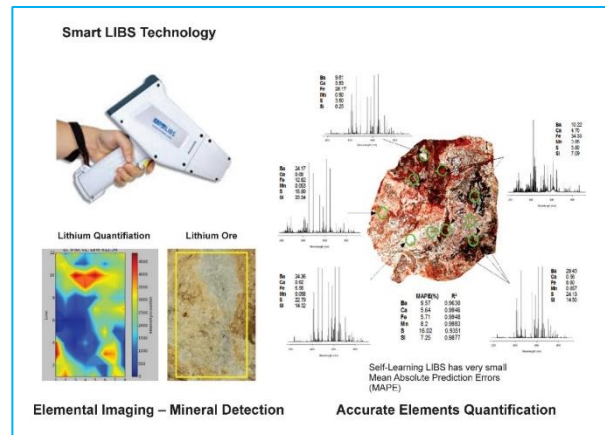


INSite Project

In situ ore grading system using LIBS in harsh environments, funded by EIT Raw Materials a body of the European Commission, on going project

+ info1: <https://twitter.com/INSiteProj>

+ info2: <https://www.linkedin.com/in/insite-project/>



First Prototype tested by potential customer, prepared for field tests

Field Tests in real environment - aggregate production facility in Žerjav, Slovenia

• (October 2022)



EITRM115926

O4.2 Demonstrator of a
Portable LIBS system



Space Geo- Exploration Project: Development of Geo-Technologies



NASA'S FLIGHT OPPORTUNITIES PROGRAM

APPLIED ASTRONAUTICS PROGRAM

International Institute for Astronautical Sciences

DEVELOP TECHNOLOGIES

EXTREME ENVIRONMENTS

ENGINEERING SPACE AND SEA

SPACE-EARTH-SEA INTERACTION

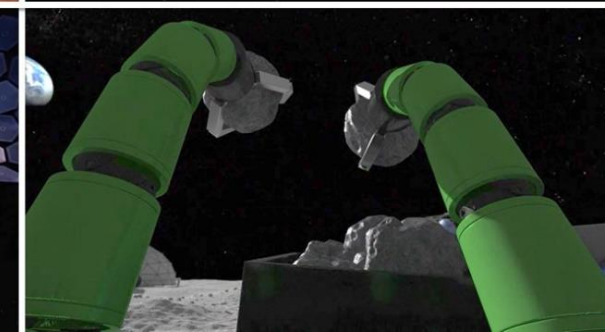
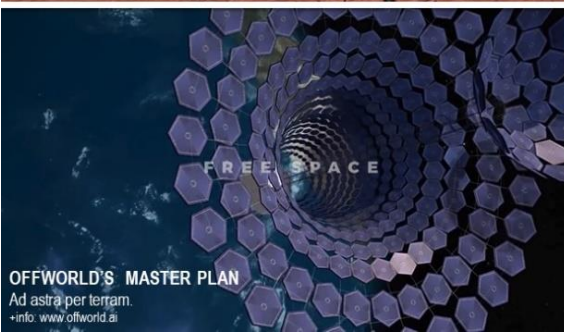
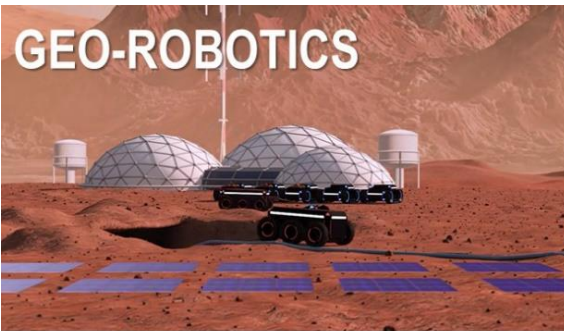


NASA and ESA tests system for recovering downed astronauts on the moon

One step closer to prospecting the moon

by European Space Agency

SPACE RESOURCES (ISRU CONCEPT)



SPACE GEO-EXPLORATION

SPACE MINING

Looking ahead... Towards the Future!

- Underwater perception a major research
- New sensing capabilities
 - Hyperspectral
 - In situ – spectroscopy
 - Biological information sensing and in situ processing
 - ...
- New approaches for information interpretation (AI, distributed multiple system based, etc)
- Pushing the boundaries of underwater robotic technology with innovative applications
 - Long term permanence
 - Underwater cargo transport
 - Seabed processing
 - ...
- Other emergent **R**esearch **L**ines
 - Space Geo-Robotics and Geo-Technologies
 - Space Resources and Space Mining
 - ...



Students Opportunities



- **To work aligned with the Research Lines previously presented**
 - *Or other thematic that can merge with our main topics (after analysis and discussion with our Coordinator)*
- **Educational Internships**
- **Master Thesis Supervising**
- **Or (when possible) internship or research development under the scope of a project**
- The possibility to work very closely with our researchers and networking (several partners involved in many of our projects)
- Transfer Technology learning (Industry connection)

THANK YOU FOR YOUR ATTENTION...

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